CPSC 362 Lecture - poof

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Timestamps

07:38:48 PM

Okay so he's talking mainly about the project and how far along people are. People tend to not be incredibly far only a handful of people have created an FSM. He said he is considering adjusting the project depending on our position and understanding of the project.

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Now he is going back to talking about how to implement a DFSM into code. He's sorta doing psuedo-code mentioned below. Figure 4

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Taking a break then going to go over non-deterministic FSM (and NFAs).

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You can get 90% on the project if you document a FSM and diagram it without code. FYI. Basically 90% for desired output, 100% for intended FSM.

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Basically he's been making corrolations between video game idles and NFSM. He also mentioned that this will be useful for regexp next week.

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Next time, we are converting NFSM to DFSM. So make sure to understand FSM. lol

^{*}Dedicated to @QuesoGrande

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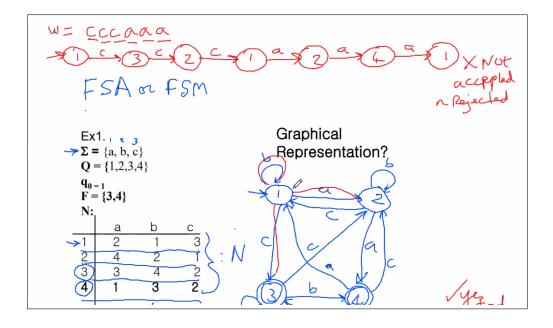
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1 FSM Recap

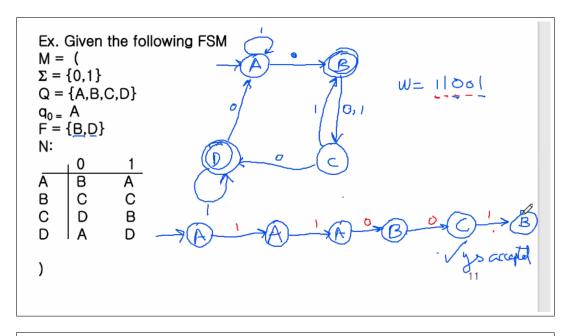
A finite-state machine (FSM) or finite-state automaton (FSA, plural: automata), finite automaton, or simply a state machine, is a mathematical model of computation. It is an abstract machine that can be in exactly one of a finite number of states at any given time. The FSM can change from one state to another in response to some inputs; the change from one state to another is called a transition.

An FSM is defined by a list of its states, its initial state, and the inputs that trigger each transition. Finite-state machines are of two types—deterministic finite-state machines and non-deterministic finite-state machines.

A deterministic finite-state machine can be constructed equivalent to any non-deterministic one.



2 Chapter 2.2 - Deterministic FSM



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c) Implementation of a DFSM

function DFSM (ω: string)

table = array [1..nstates, 1..nalphabets] of integer; /* Table N

for the transitions*/

{

state = 1; (the starting state)

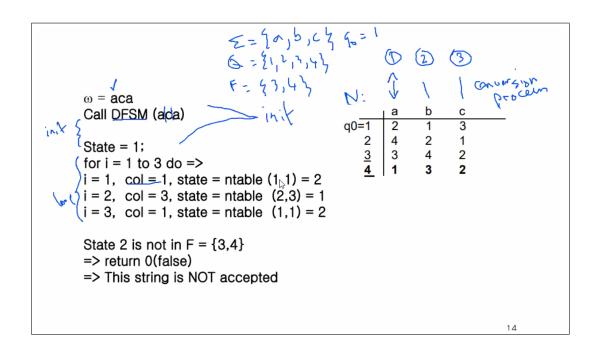
for i = to length (ω) do

{

col = char_to_col (ω[i]);

state = table[state, col];
}

if state is in F then return 1 /* accept */
else return 0
}
```



3 Chapter 2.3 - Non-Deterministic FSM (NFSM)

```
Def: NFSM= (Σ, Q, q0, F, N)

Where Σ = a finite set of input symbols

Q = a finite set of states
q<sub>0 ∈ Q</sub> is the starting state
F ⊆ Q is a set of accepting state empty Set = {
N: Q x (Σ U ε) → P(Q)

Two differences from DFSM
1. Input is expanded by epsilon => can go to a different state without reading any input

2. Can go to multiple states given an input
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Ex 1. NFSM with Multiple States Transitions
$$M = \{ \Sigma = \{a,b\}, Q = \{1,2,3\}, q_{0=1}, F = \{2,3\} \}$$
N:
$$\frac{a}{1} = \begin{cases} \{1,2\} & \{1\} \\ \{2\} & \{1,3\} \\ \{2,3\} & \{1,3\} \end{cases}$$

$$\frac{\{2,3\}}{3} = \begin{cases} \{2,3\} & \{1,3\} \\ \{2,3\} & \{1,3\} \end{cases}$$

